

# Imaging Fourier Transform Spectrometer: Balloon Instrument Development Update

A photograph showing a large white balloon being inflated by a tractor in a field. The tractor is on the left, and the balloon is in the center. A person is standing on the tractor. In the background, another smaller white balloon is being inflated. The scene is outdoors with trees and a cloudy sky.

Tom McElroy, York University

With Contributions by:

Zahra Vaziri, Gurpreet Singh

Rehan Siddiqui

Double Balloon Launch  
September 1983  
Palestine, Texas

# Imaging Fourier Transform Spectrometer Topics for Today:

- Background
- Development Team
- Science Goals
- Hardware development
- The path forward
- Acknowledgements

# Development Team

- Zahra Vaziri Ph.D. candidate and project leader
  - Mechanical design
  - Instrument operating software (data acquisition)
  - Pointing system design and test
- Gurpreet Singh M.Sc. Candidate
  - Interferometer testing
  - Data acquisition and analysis
- Rehan Siddiqui Post Doctoral Fellow
  - Data analysis
  - Line-by-line model and retrieval software (just started)
- Chen Zheng Post Doctoral Fellow
  - Pointing system software (moved on)
- David Barton M.Sc. Research Associate
  - Electronics support
  - Logistics
  - Student supervision

# Arctic Science

Thermal balance in the Arctic:  $F = \sigma T^4$

If the temperature changes, the flux changes by:  $dF/dT = 4 \sigma T^3$

So the change in temperature needed to rebalance after a change in  $F$

$$dT = dF / (4 \sigma T^3)$$

So the change in **temperature** needed for a given **dF** is larger for a system at lower temperature.

Example: Compare midlatitudes at 273 K to the Arctic at 225 K

$$(273/225)^3 = 1.79$$

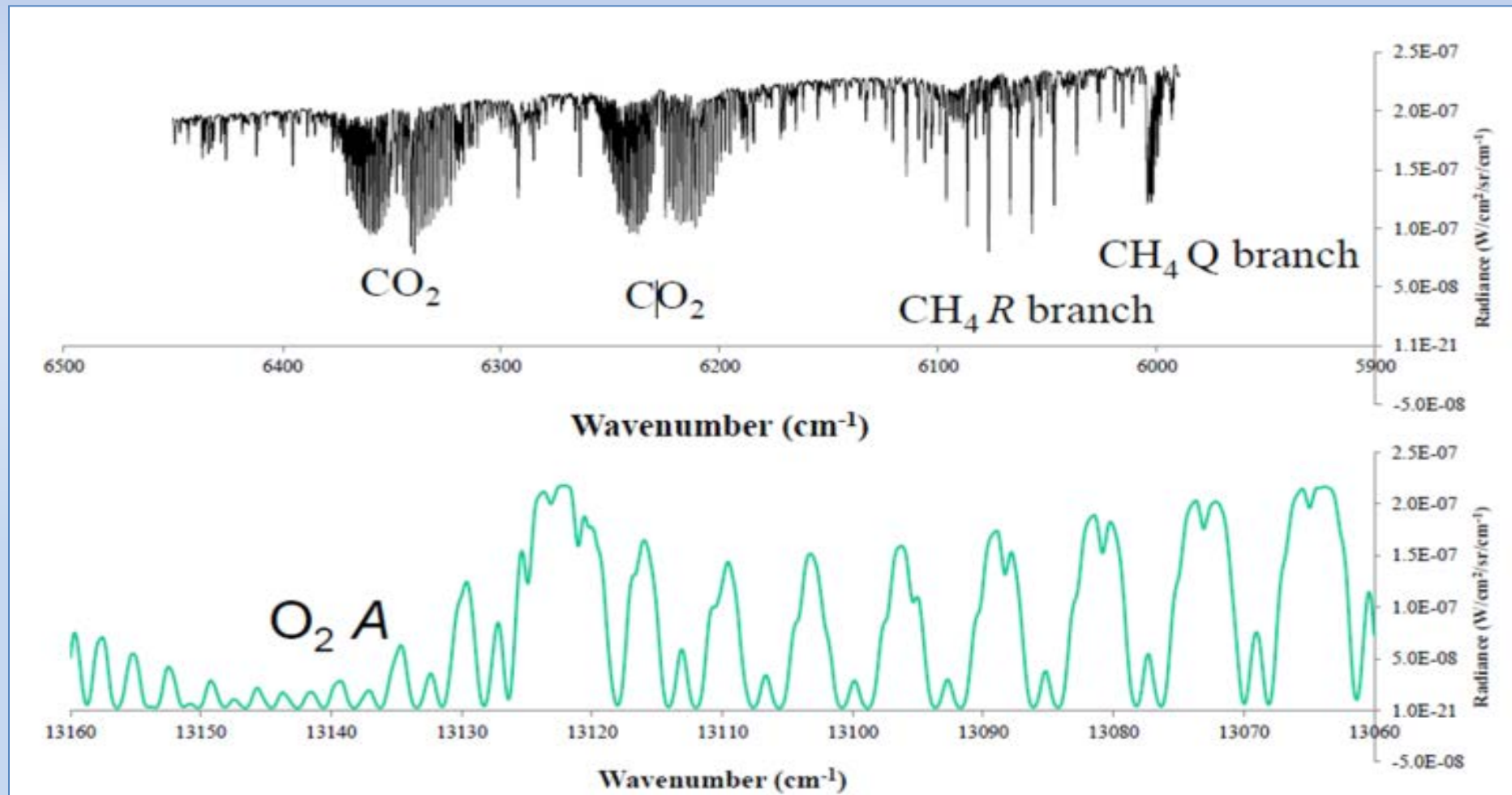
Of course this is multiplied by the effect on radiation as the ice melts (in summer)

**Concern: Melting permafrost might release  $\text{CH}_4$  and  $\text{CO}_2$**

# Measurements

- Concept originally discussed at a workshop in Banff in 2006
- The PHEOS mission put forward by Jack McConnell and McElroy in 2011
- Went through several phases as a possible add-on to PCW (Polar Communications and Weather Satellite) but PCW went on hold under the Harper government
- CSA funded the work presented here in 2014 to investigate instrument performance issue
- An independent system study is being funded by CSA at ABB with input from Environment and Climate Change Canada (R. Nassar, C. McLinden)

# 1.6 micron and 762 nm





# PHEOS

## Polar Highly Elliptical Orbit Science

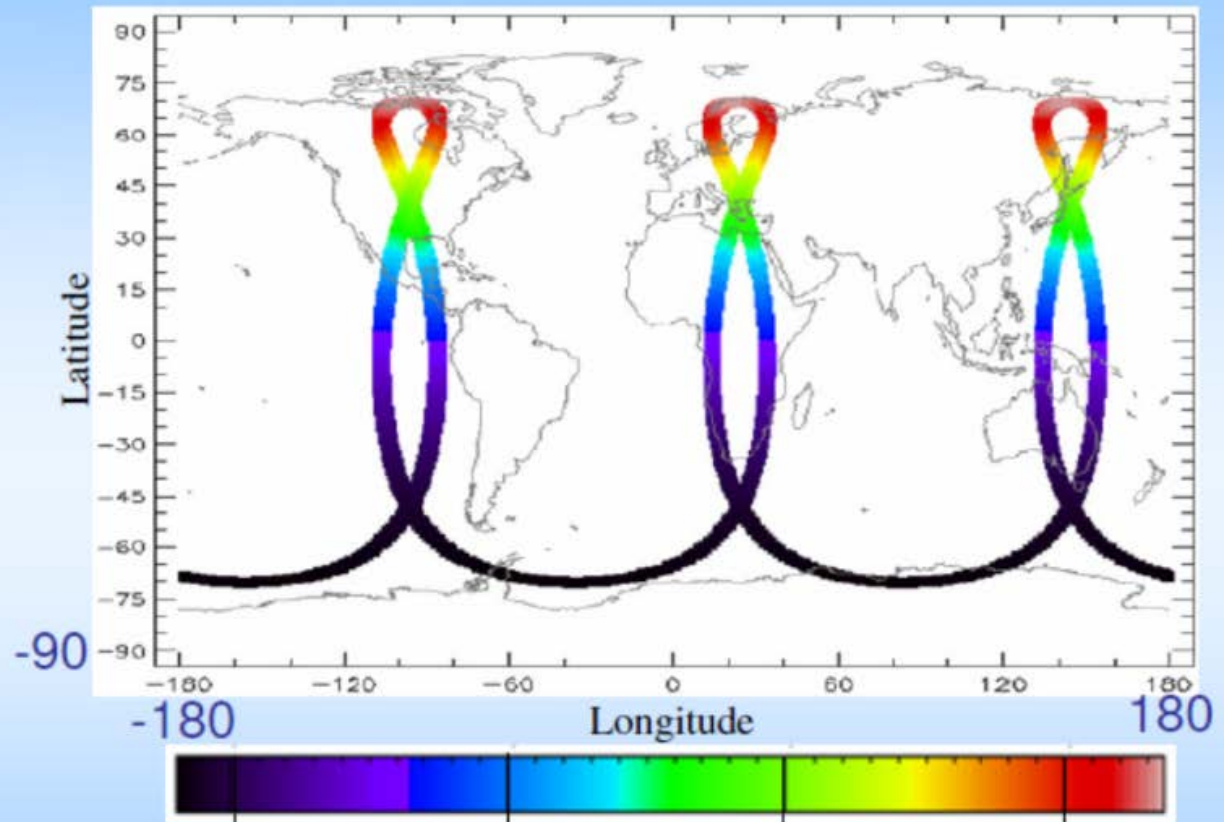
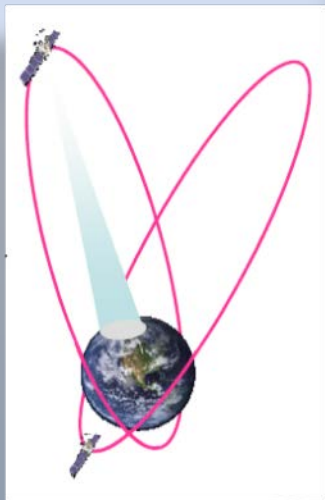
### Proposed space mission (PHEOS Alone):

- Environment and Climate Change Canada Initiative
- Two satellites in a three-apogee, highly elliptical orbit
- Quasi-geosynchronous, continuous temporal coverage
- Weather and atmospheric composition data
- Science Payload: Polar Highly Elliptical Orbit Science-Weather Climate and Air quality (PHEOS-WCA)
- Composed of
  - **Imaging IR Fourier transform Spectrometer (IFTS)**
  - Possibly including a UV-VIS spectrometer
  - Weather imager

# Three Apogee Orbit

Goal: Geosynchronous-like view of the Arctic

TAP Orbit Ground Track



Suggested apogees: 95°W, 25°E, 145°E



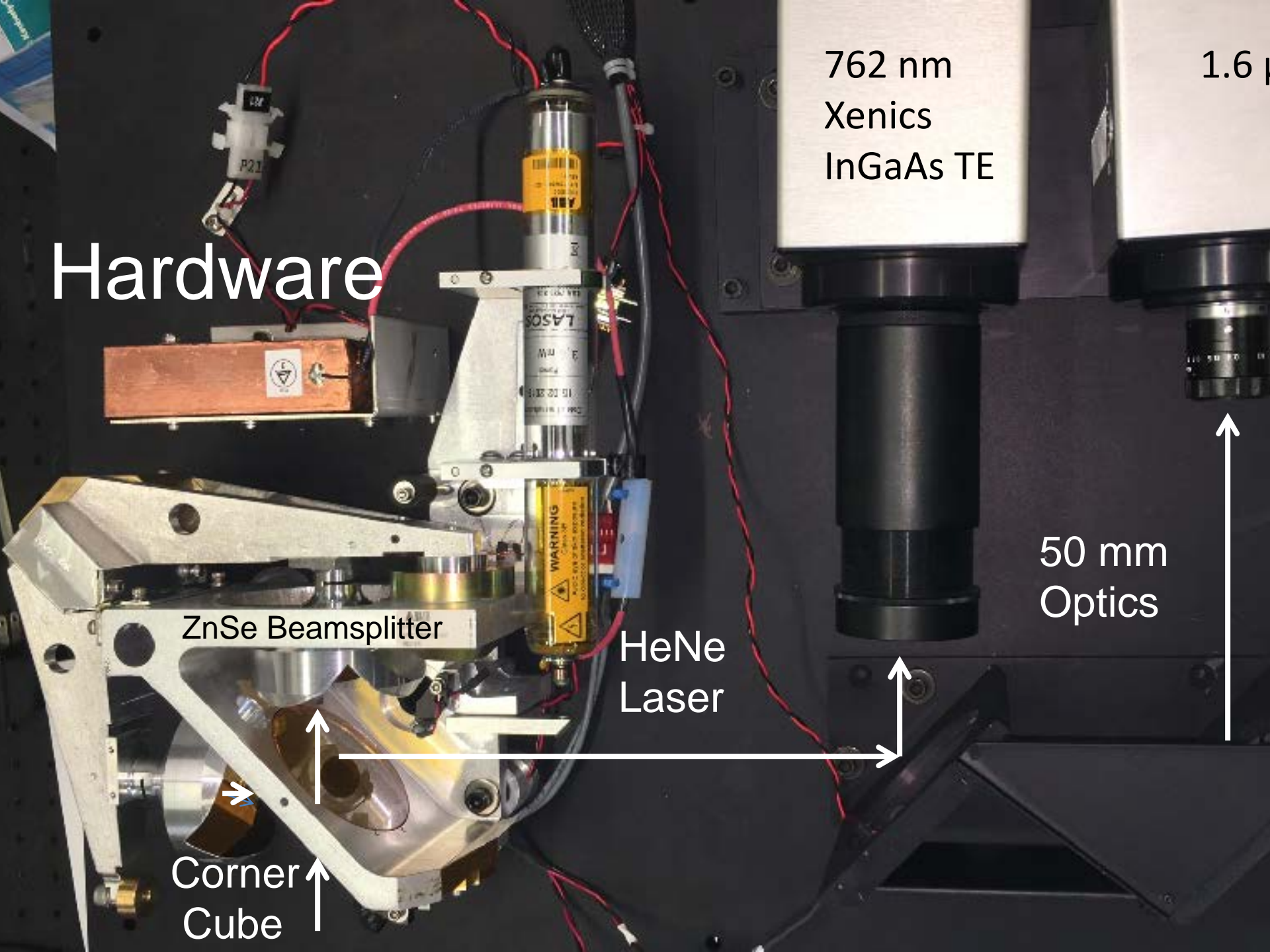
# Balloon Project

Improve the technical readiness  
of the Imaging Fourier Transform concept

Supported by a grant from the Canadian  
Space Agency (CSA) to develop a balloon-based  
demonstrator

The proposal includes developing a pointing  
mirror system and an IFTS

# Hardware



762 nm  
Xenics  
InGaAs TE

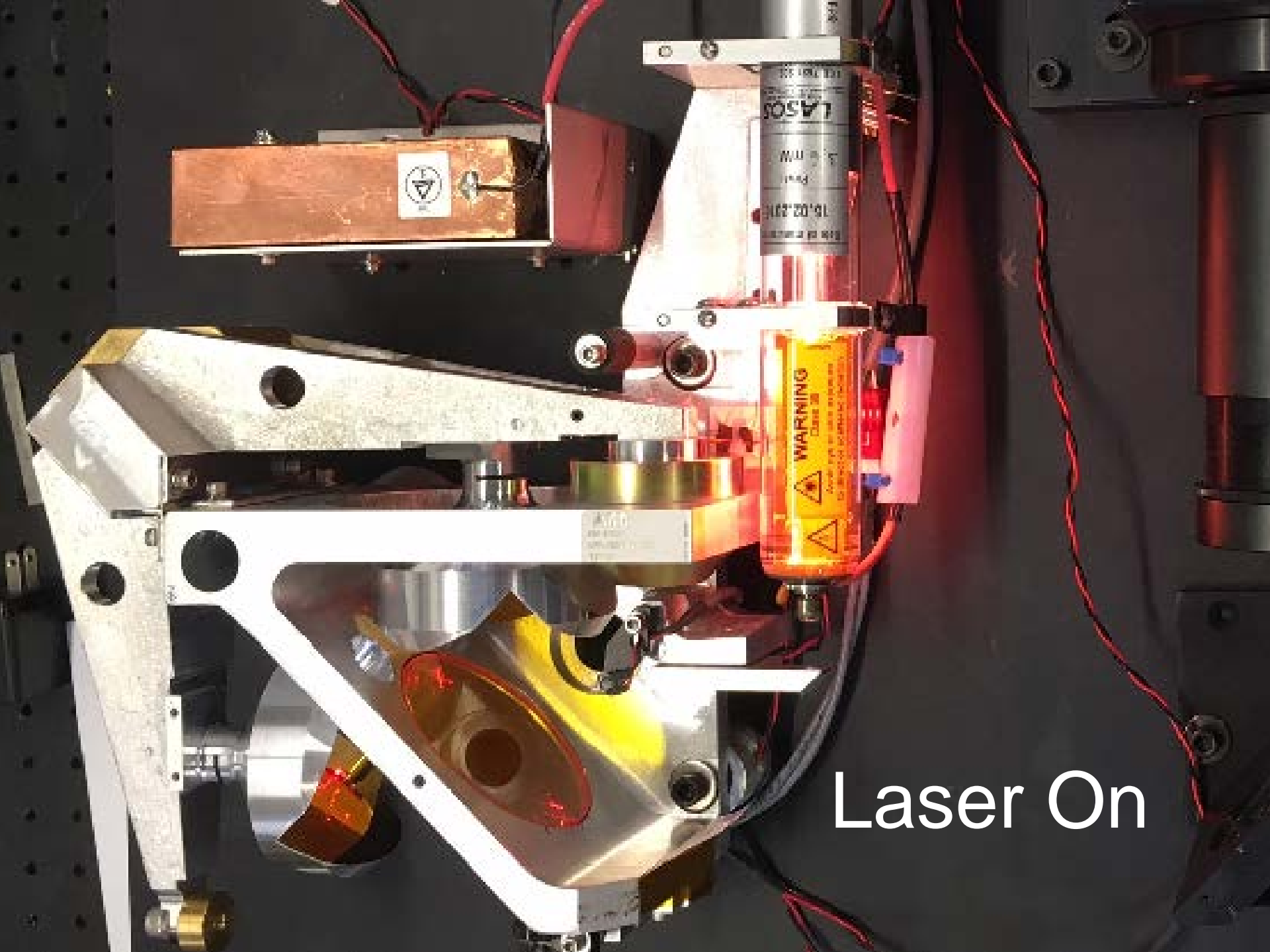
1.6 m

50 mm  
Optics

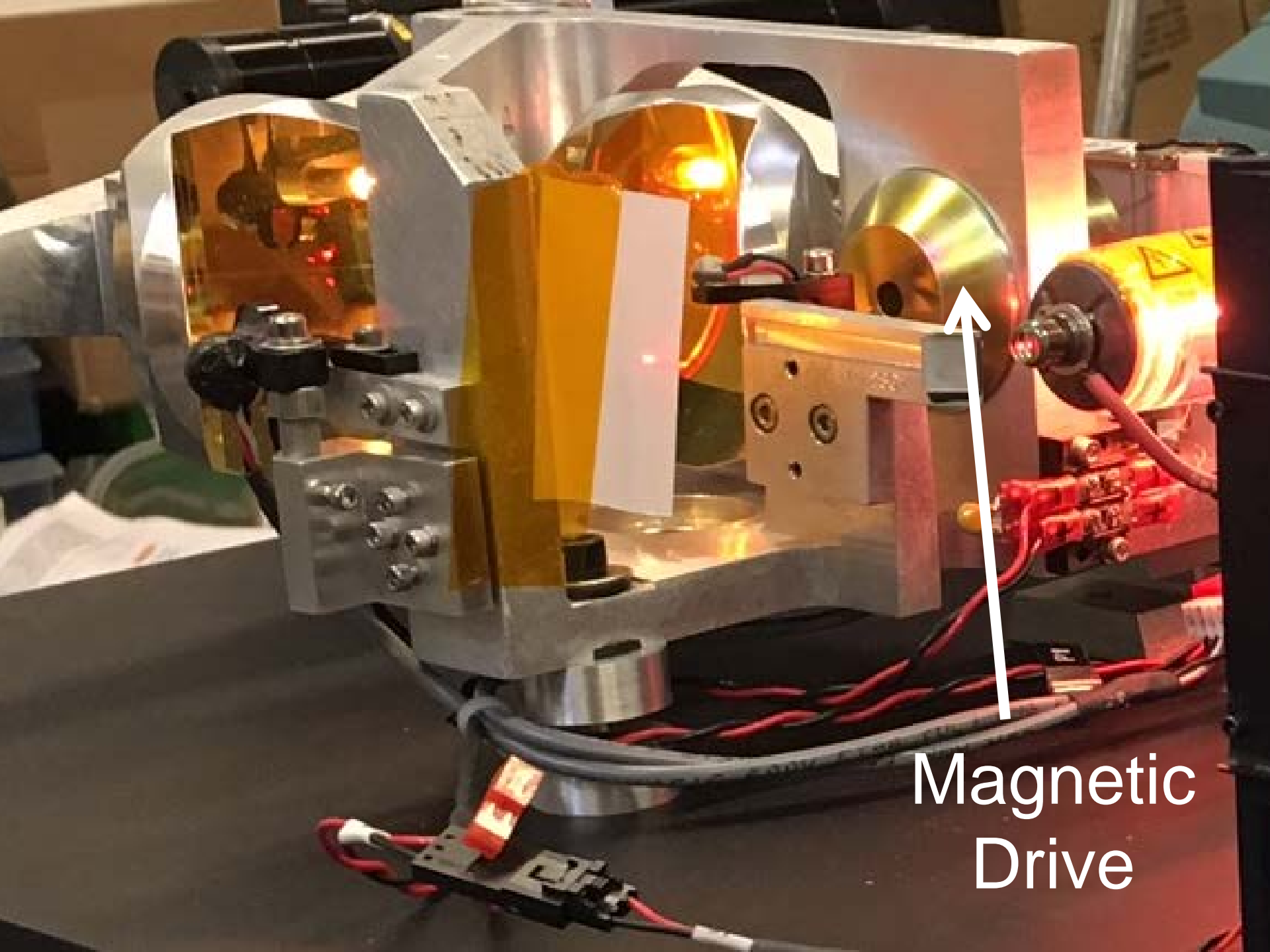
ZnSe Beamsplitter

HeNe  
Laser

Corner  
Cube



Laser On



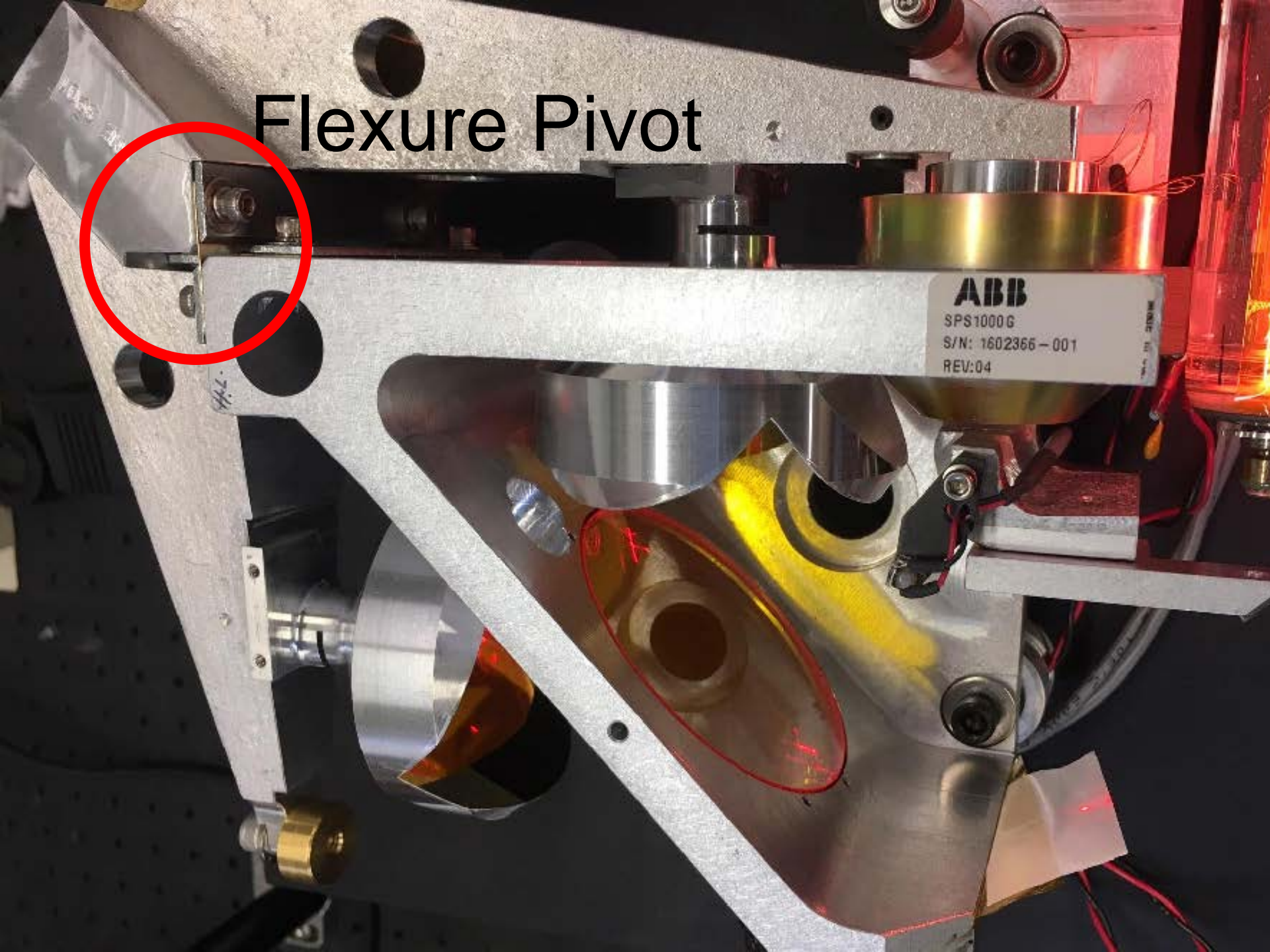
Magnetic  
Drive



Flexure Pivot



**ABB**  
SPS1000G  
S/N: 1602366 - 001  
REV:04



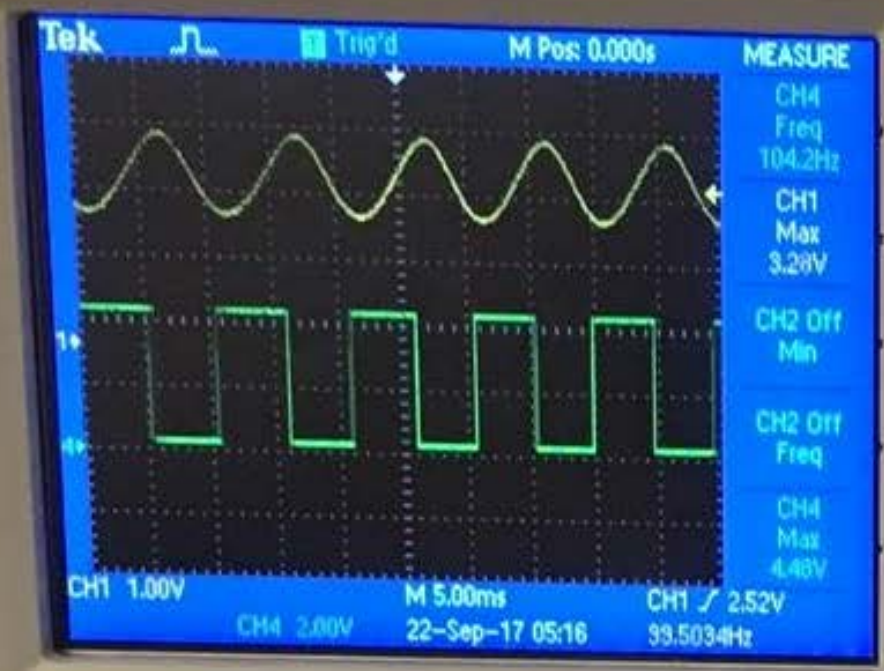


# ABB Control Box





Tektronix TPS 2024B FOUR CHANNEL DIGITAL STORAGE OSCILLOSCOPE 200 MHz 2 GS/s



AutoRange Save/Recall Measure Acqui Application Utility Cursor Displa Trig View Force Trig Set To 50%

Vertical Position Menu Scale

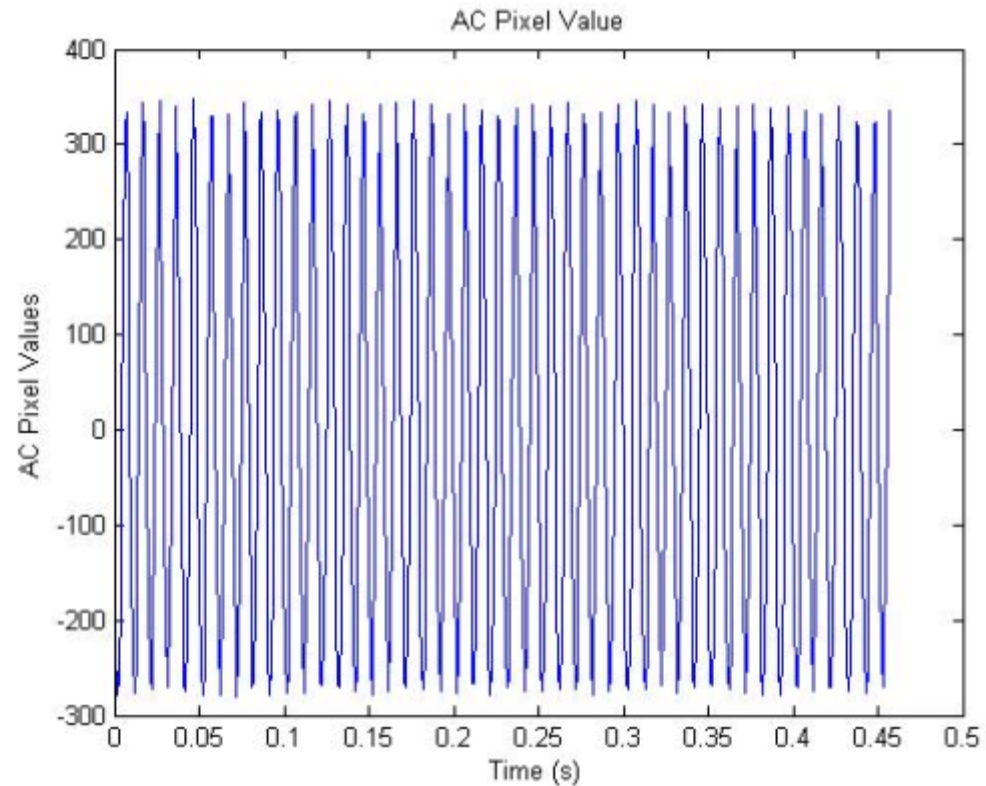
1 Math 2 3

SEE BACK PANEL FOR RATINGS

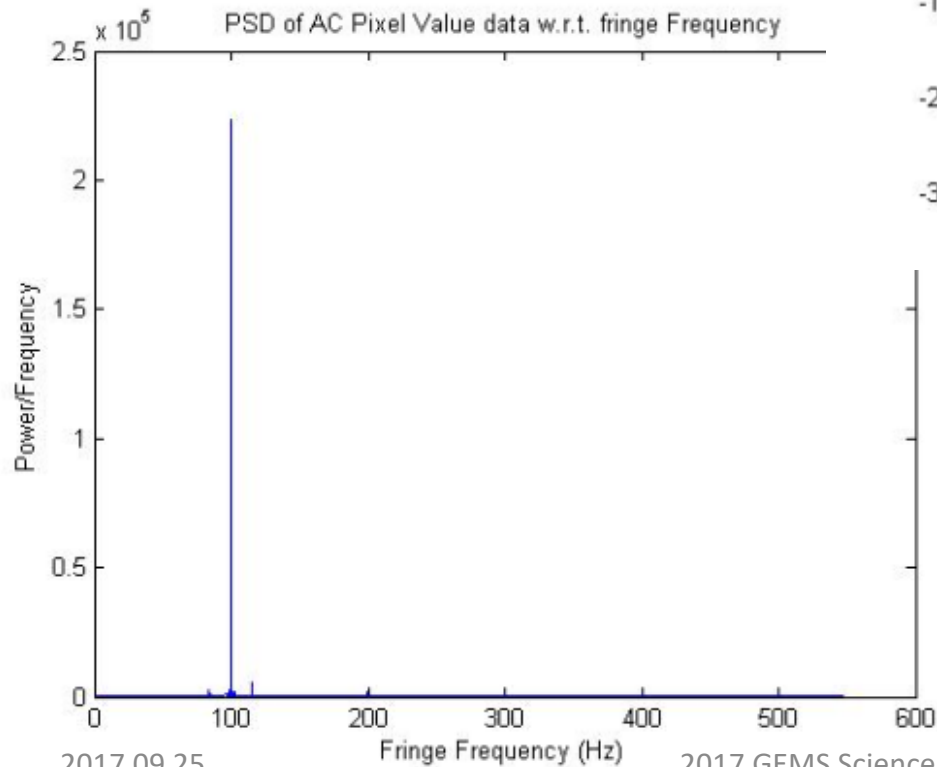
Metrology Laser Fringes

# Laser Output

With 500 data points:



With 10,000 points:



# The Path Forward

- The original plan was to be flying the instrument with Geoff Toon on a Mk IV interferometer flight in September (like NOW!)
- Delays in getting components and problems integrating the cameras led to delays
- The election of Donald Trump made Zhara PNG
- Decision was made to take the pressure off the students and do ground-based testing instead

# Status

- Pointing system was validated on a balloon flight in September of 2015
- A heliostat mount was designed and installed in the roof hatch of the lab at York (will borrow U of T heliostat)
- Resolution tests (spectral and spatial) will be carried out in the coming months.
- Retrievals of the gases will be done using solar spectra of diffuse light scattered off a spectralon diffuser in the lab
- If the situation at York permits, we will seek support for a balloon flight next year



Thank You for  
Your Attention



The End!

# Funding for this work was provided by:



The CSA/ABB/NSERC Industrial Research Chair in Atmospheric Remote sounding at York University



CSA

ASC

The Canadian Space Agency Agence spatiale canadienne

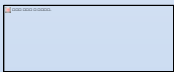


ABB Incorporated, Quebec City, Canada



Natural Sciences and Engineering  
Research Council of Canada

Conseil de recherches en sciences  
naturelles et en génie du Canada



Acknowledgement:  
David Barton, York University



# Camera Specs

[PRODUCTS](#)
[APPLICATIONS](#)
[INDUSTRIES](#)
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**Xeva-1.7-320 TE3**

[Info](#)
[Features](#)
[Specifications](#)
[Accessories](#)
[Camera](#)

**Array Specifications**

Camera Specifications

## Array Specifications

### Xeva-1.7-320 TE3

Array type	InGaAs
Spectral band	0.9 $\mu\text{m}$ to 1.7 $\mu\text{m}$ (VisNIR optional 0.4 to 1.7 $\mu\text{m}$ )
Resolution	320 x 256
Pixel pitch	30 $\mu\text{m}$
Array cooling	TE3-cooled
Pixel operability	> 99 %

# Xenics Specifications

All cameras are equipped with a 320 by 256 InGaAs array

ALL DATA ARE TYPICAL VALUES AND CAN VARY FROM DETECTOR TO DETECTOR

NOTE THAT ALL CAMERAS HAVE A 14-BIT ADC EXCEPT FOR CERTAIN DEMO CAMERAS

Camera model	XEVA USB 100Hz		Camera model	XEVA with CameraLink 100 Hz	
<b>USB 2.0 interface</b>			<b>CAMERALINK interface</b>		
<b>Thermo-electric cooler - note 1</b>	<b>TE1</b>	<b>TE1</b>	<b>Thermo-electric cooler - note 1</b>	<b>TE1</b>	<b>TE1</b>
Gain	LOW	HIGH	Gain	LG	HG
ADC [bits]	12	12	ADC [bits]	14	14
Tsat [sec] - note 5	300	15	Tsat [sec] - note 5	300	15
Cfb [fF] (integration capacitor)	200	10	Cfb [fF] (integration capacitor)	200	10
Vout [V] of the ADC	3	3	Vout [V] of the ADC	3	3
Qsat full well [#electrons]	3750000	187500	Qsat full well [#electrons]	3750000	187500
dQsat/dt [C/sec]	2E-15	2E-15	dQsat/dt [C/sec]	2E-15	2E-15
Idark [electrons/sec]	12500	12500	Idark [electrons/sec]	12500	12500
QE	0.8	0.8	QE	0.8	0.8
Flux [photons/sec] - note 2	15625	15625	Flux [photons/sec] - note 2	15625	15625
Vout per ADU [V/ADU]	0.000732422	0.000732422	Vout per ADU [V/ADU]	0.000183105	0.000183105
Sensitivity [V/electron]	0.0000008	0.000016	Sensitivity [V/electron]	0.0000008	0.000016
Sensitivity [electrons/ADU]	915.5273438	45.77636719	Sensitivity [electrons/ADU]	228.8818359	11.4440918
Sensitivity [photons/ADU]	1144.40918	57.22045898	Sensitivity [photons/ADU]	286.1022949	14.30511475
<b>Noise</b>			<b>Noise</b>		
ADU <sub>rms</sub> (MEASURED; T <sub>int</sub> =100us)	1.2	2.5	ADU <sub>rms</sub> (MEASURED; T <sub>int</sub> =100us)	6.3	13.9
V <sub>rms</sub> electrons	0.000878906	0.001831055	V <sub>rms</sub> electrons	0.001153564	0.002545166
NEW - note 3	1.94238E-16	2.02332E-17	NEW - note 3	2.54938E-16	2.81241E-17
NEP (T <sub>int</sub> =1msec)	1.94238E-13	2.02332E-14	NEP (T <sub>int</sub> =1msec)	2.54938E-13	2.81241E-14
<b>S/N ratio [dB]</b>	70.66357404	64.28839879	<b>S/N ratio [dB]</b>	68.3015878	61.42810278
<b>RO Noise @ 250 K [electrons] - note 4</b>	380	50	<b>RO Noise @ 250 K [electrons] - note 4</b>	380	50

Note 1: TE1 detector temperature is 250K

Note 2: this is the photon flux as represented by the dark current

Note 3: just for intermediate calculation purposes

Note 4: in general the Read-Out Noise is lower than the system noise

Note 5: For practical reasons the camera limits the

integration time to 8 msec in HG and 200 msec in LG

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Note 6: ADU<sub>rms</sub> measured with 12 bits rather than 14 bits for CL vs. USB.